## AE31002 Aerospace Structural Dynamics Forced Vibration of Beam

Anup Ghosh

A (1) < 3</p>



Let a beam subjected to the inertial forces from the vibrations of two different modes,  $\Phi_m(x)$  and  $\Phi_n(x)$ . Corresponding inertial forces are shown in the figure. The inertial force is obtained from the multiplication of mass per unit length and the acceleration amplitude, i.e.,  $f_{ln} = \bar{m}(x)\omega_n^2\Phi_n(x)$ 

## Betti's Theorem

for a linear elastic structure subject to two sets of forces  $\{P_i\}$  and  $\{Q_j\}$ , the work done by the set P through the displacements produced by the set Q is equal to the work done by the set Q through the displacements produced by the set P.

Accordingly, the work done by the inertial force,  $f_{In}$ , acting on the displacements of mode m is equal to the work of the inertial force,  $f_{In}$ , acting on the displacement of mode n, i.e.,

$$\int_{0}^{L} \Phi_{m}(x) f_{ln} dx = \int_{0}^{L} \Phi_{n}(x) f_{lm} dx$$
$$\omega_{n}^{2} \int_{0}^{L} \Phi_{m}(x) \bar{m}(x) \Phi_{n}(x) dx = \omega_{m}^{2} \int_{0}^{L} \Phi_{n}(x) \bar{m}(x) \Phi_{m}(x) dx$$
$$(\omega_{n}^{2} - \omega_{m}^{2}) \int_{0}^{L} \Phi_{m}(x) \bar{m}(x) \Phi_{n}(x) dx = 0$$
Since  $\omega_{n} \neq \omega_{m}$  The modes are orthogonal to each other.



Following small deflection theory and the force terms, shear and moments, as function of both  $\times$  & t, equation of motion perpendicular to the beam is

$$V - \left(V + \frac{\partial V}{\partial x}\right) + p(x, t)dx - \bar{m} dx \frac{\partial^2 y}{\partial t^2} = 0$$

where  $\bar{m}$  is mass/unit length, so the relation simplifies to,

$$\frac{\partial V}{\partial x} + \bar{m} \frac{\partial^2 y}{\partial t^2} = p(x, t)$$

A ■

From the simple bending theory and following the present direction of co-ordinate and forcing, the moment curvature relation is

$$M = EI \frac{\partial^2 y}{\partial x^2}$$
 and  $V = \frac{\partial M}{\partial x} \Rightarrow V = EI \frac{\partial^3 y}{\partial x^3}$ 

Now substituting this in the equation of motion, we have

$$EI\frac{\partial^4 y}{\partial x^4} + \bar{m}\frac{\partial^2 y}{\partial t^2} = p(x,t)$$

A partial differential equation of fourth order, considering only transverse flexural deflection. (The deflection associated with the shear force and associated rotary moment of inertia is not considered here – Timoshenko's beam theory)

Let us assume that the general solution of the of this equation is

$$y(x,t) = \sum_{n=1}^{\infty} \Phi_n(x) z_n(t)$$

The normal modes  $\Phi_n(x)$  satisfy the basic differential equation  $\Phi^{IV}(x) - a^4 \Phi(x) = 0$  and since  $a^4 = \frac{\bar{m}\omega^2}{EI}$ .

$$EI \Phi_n^{IV} = \bar{m}\omega_n^2 \Phi_n(x), \qquad n = 1, 2, 3, \dots$$

To satisfy the force boundary condition, let us substitute it to the previous equation

$$EI \sum_{n} \Phi_{n}^{IV}(x) z_{n}(t) = p(x, t) - \bar{m} \sum_{n} \Phi_{n}(x) \ddot{z}_{n}(t)$$
$$\sum_{n} \bar{m} \omega_{n}^{2} \Phi_{n}(x) z_{n}(t) = p(x, t) - \bar{m} \sum_{n} \Phi_{n}(x) \ddot{z}_{n}(t)$$

Multiplying both sides of the equation by  $\Phi_m(x) dx$  and integrating between 0 to L and using the orthogonality condition, we have

$$\omega_m^2 z_m(t) \int_0^L \bar{m} \Phi_m^2 \, dx = \int_0^L \Phi_m(x) p(x,t) \, dx - \ddot{z}_m(t) \int_0^L \bar{m} \Phi_m^2 \, dx$$

Now in a generalized form

$$M_n \ddot{z}_n(t) + \omega_n^2 M_n z_n(t) = F_n(t), \qquad n = 1, 2, 3, \dots$$
$$\ddot{z}_n(t) + \omega_n^2 z_n(t) = \frac{F_n(t)}{M_n}$$

where,  $M_n = \int_0^L \bar{m} \Phi_n^2 dx$  is known as the **modal mass** and  $F_n(t) = \int_0^L \Phi_n(x) p(x, t) dx$  is known as the **modal force.** 

イロン イヨン イヨン イヨン

Consider a simply supported uniform beam subjected to a concentrated constant force suddenly applied at a section  $x_1$  units from the left support. Determine the response using modal



The mode shapes of a simply supported beam are

$$\Phi_n = \sin \frac{n\pi x}{L}, \qquad n = 1, 2, 3, \dots$$

and the modal force is

$$F_n(t) = \int_0^L \Phi_n(x) p(x,t) \ dx$$

< ロ > < 回 > < 回 > < 回 > < 回 > <

2

In this problem  $p(x,t) = p_0$  and  $x = x_1$  otherwise p(x,t) = 0.

$$F_n(t) = P_0 \Phi_n(x_1) \Rightarrow P_0 \sin \frac{n\pi x_1}{L}$$

The modal mass is

$$M_{n} = \int_{0}^{L} \bar{m} \Phi_{n}^{2} \, dx = \int_{0}^{L} \bar{m} \, \sin^{2} \frac{n\pi x}{L} \, dx = \frac{\bar{m}L}{2}$$

Substituting the value of modal force in the equation  $\ddot{z}_n(t) + \omega_n^2 z_n(t) = \frac{F_n(t)}{M_n}$  we get

$$\ddot{z}_n(t) + \omega_n^2 z_n(t) = \frac{P_0 \sin \frac{n\pi x_1}{L}}{\bar{m}L/2}$$

Following the standard solution of the undamped SDOF sytem for suddenly applied load,

$$z_n = (z_{st})_n (1 - \cos \omega_n t)$$

æ.

Here 
$$(z_{st})_n = rac{2P_0 \sin rac{n\pi x_1}{L}}{\omega_n^2 \overline{m} L}$$

So, 
$$z_n = \frac{2P_0 \sin \frac{n\pi x_1}{L}}{\omega_n^2 \bar{m} L} (1 - \cos \omega_n t)$$

The modal deflection at any section of beam is

$$y_n(x,t) = \Phi_n(x)z_n(t)$$
$$y_n(x,t) = \frac{2P_0 \sin \frac{n\pi x_1}{L}}{\omega_n^2 \bar{m}L} (1 - \cos \omega_n t) \sin \frac{n\pi x}{L}$$

The total deflection is then

$$y(x,t) = \frac{2P_0}{\bar{m}L} \sum_n \left[ \frac{1}{\omega_n^2} \sin \frac{n\pi x_1}{L} (1 - \cos \omega_n t) \sin \frac{n\pi x}{L} \right]$$

$$x_1 = L/2$$

#

$$y_n(x,t) = \frac{2P_0}{\bar{m}L} \sum_n \left[ \frac{1}{\omega_n^2} \sin \frac{n\pi}{2} (1 - \cos \omega_n t) \sin \frac{n\pi x}{L} \right]$$

- $\#\,$  No even mode contribute to the deflection of the beam.
- # Position of the excitation is one of the nodes of even modes, so those do not get excited.
- # Amplitude of modal displacement is a measure of a certain mode.
- # Amplitude is dependent on dynamic load factor  $(1 \cos \omega_n t)$ (max value 2) and  $1/\omega_n^2$ , i.e., 1; 1/81; 1/625 etc.



Anup Ghosh Forced Vibration