## AE31002 Aerospace Structural Dynamics Approximate Methods

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Rayleigh's Method Rayleigh-Ritz method

We have seen in two examples that if the transverse deflection of a beam is given as the multiplication of a shape function and a sinusoidal trigonometric time function, like,  $w(x,t) = W(x) \cos \omega t$ , the kinetic energy becomes

$$T = \frac{1}{2} \int_0^l \dot{w}^2 \, dm = \frac{1}{2} \int_0^l \dot{w}^2 \rho A(x) \, dx$$
$$T_{max} = \frac{\omega^2}{2} \int_0^l \rho A(x) W^2(x) \, dx$$

The potential energy of the beam V is the same as the work done in deforming the beam. Disregarding the work done by shear force,

$$V=\frac{1}{2}\int_0^l M \ d\theta$$

Substituting the value of  $M = EI \frac{\partial^2 w}{\partial x^2}$  and  $\theta = \frac{\partial w}{\partial x}$ 

The potential energy become

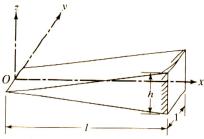
$$V = \frac{1}{2} \int_0^l EI(x) \left(\frac{\partial^2 w}{\partial x^2}\right)^2 dx \quad \text{and}$$
$$V_{max} = \frac{1}{2} \int_0^l EI(x) \left(\frac{d^2 W(x)}{dx^2}\right)^2 dx$$

Now equating the max energy expressions we obtain the **Rayleigh's quotient** 

$$R(\omega) = \omega^{2} = \frac{\int_{0}^{l} EI(x) \left(\frac{d^{2}W(x)}{dx^{2}}\right)^{2} dx}{\int_{0}^{l} \rho A(x)W^{2}(x) dx}$$

$$R(\omega) = \omega^{2} = \frac{\int_{0}^{l_{1}} E_{1}l_{1} \left(\frac{d^{2}W(x)}{dx^{2}}\right)^{2} dx + \int_{l_{1}}^{l_{2}} E_{2}l_{2} \left(\frac{d^{2}W(x)}{dx^{2}}\right)^{2} dx + \dots}{\int_{0}^{l_{1}} \rho A_{1}(x)W^{2}(x) dx + \int_{l_{1}}^{l_{2}} \rho A_{2}(x)W^{2}(x) dx + \dots}$$

# Find the fundamental frequency of transverse vibration of the nonuniform cantilever beam shown below using the deflection shape W(x) = (1- x/l)^2.



The cross sectional area and the moment of inertia of the transverse cross section about centroidal axis are

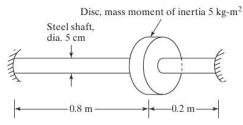
$$A(x) = \frac{hx}{l}$$
 and  $I(x) = \frac{1}{12} \left(\frac{hx}{l}\right)^3$ 

## From the Rayleigh's quotient

$$\omega^{2} = \frac{\int_{0}^{l} E \frac{1}{12} \left(\frac{hx}{l}\right)^{3} \left(\frac{2}{l^{2}}\right)^{2} dx}{\int_{0}^{l} \rho \left(\frac{hx}{l}\right) \left(1 - \frac{x}{l}\right)^{4} dx} = 2.5 \frac{Eh^{2}}{\rho l^{4}}$$

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## # Using Rayleigh's method, determine the fundamental natural frequency of the system



For a shaft under torsion, the shear stress  $\tau$  at a distance r from the center of the shaft is given by

$$\tau = \frac{M_t(x) r}{J}$$

Potential energy in terms of strain energy is

$$V = \frac{1}{2} \int \left(\frac{\tau}{G} \cdot \tau dA\right) dx = \frac{1}{2} \int \left(\frac{\tau^2}{G} dA\right) dx$$

As we know from the torsion of circular shaft

$$M_t(x) = GJ \frac{\partial \theta}{\partial x} \quad \Rightarrow \quad V = \frac{1}{2} \int_0^I GJ \left( \frac{\partial \theta}{\partial x} \right)^2 \, dx$$

Kinetic energy of the shaft can be written as

$$T = \frac{1}{2} \int_0^l \rho J \left(\frac{\partial \theta}{\partial t}\right)^2 dx$$

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Let us assume a harmonic variation of rotational displacement function  $\theta(\mathbf{x},\mathbf{t})$  as

 $\theta(x,t) = \Theta(x) \cos(\omega t)$ 

Now equating  $V_{max}$  and  $T_{max}$ 

$$\omega^{2} = \frac{\int_{0}^{l} GJ\left(\frac{\partial\Theta(x)}{\partial x}\right)^{2} dx}{\int_{0}^{l} \rho J \left(\Theta(x)\right)^{2} dx}$$

For a steel shaft G = 80 x 10<sup>9</sup> N/m<sup>2</sup>; and  $\rho$  g = 75.9 kN/m<sup>3</sup>

$$J = \frac{\pi d^4}{32} = \frac{\pi}{32} (0.05)^4 = 61.3594 \times 10^{-8} m^4$$

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Let us assume that  $\Theta(\boldsymbol{x})$  varies linearly on either side of the lumped mass.

$$\Theta(x) = \frac{\theta_0 x}{0.8} \text{ and } \frac{\partial \Theta}{\partial x} = \frac{\theta_0}{0.8} ; \qquad 0 \le x \le 0.8$$
  

$$\Theta(x) = \frac{\theta_0(1-x)}{0.2} \text{ and } \frac{\partial \Theta}{\partial x} = -\frac{\theta_0}{0.2} ; \quad 0.8 \le x \le 1$$
  

$$\int_0^1 GJ \left(\frac{\partial \Theta(x)}{\partial x}\right)^2 dx = 306797\theta_0^2$$
  

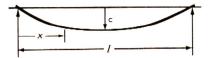
$$\int_0^1 \rho J \ (\Theta(x))^2 \ dx = 159.54 \times 10^{-5}\theta_0^2$$
  

$$\omega^2 = 1923.0292 \times 10^5 \text{ rad/sec}$$

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# Find the fundamental frequency of a simply supported beam using the deflection pattern

$$W(x) = \left(C \sin \frac{\pi x}{I}\right) \sin \omega t$$



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The second derivative of the deflection function

$$\frac{d^2 W(x)}{dx^2} = -\left(\frac{\pi}{l}\right)^2 C \sin \frac{\pi x}{l} \sin \omega t$$

From the Rayleigh quotient

$$\omega^{2} = \frac{EI\left(\frac{\pi}{I}\right)^{4} \int_{0}^{I} \sin^{2}\frac{\pi x}{I} dx}{m \int_{0}^{I} \sin^{2}\frac{\pi x}{I} dx} = \pi^{4} \frac{EI}{mI^{4}}$$

$$\omega = \pi^2 \sqrt{\frac{EI}{ml^4}}$$
 exact solution

It may be proved that for inconsistent assumption of deflected shape the estimated fundamental frequency becomes higher than the exact natural frequency.

- Rayleigh-Ritz method is an extension of the Rayleigh's energy method.
- Here we assume more shape functions or approximate deflection/representation of the structure to get more accurate frequencies and mode shapes.
- An arbitrary number of functions can be used to obtain that many number of frequencies and mode shapes.
- It also increases computation cost.
- If n arbitrary functions are chosen to describe the transverse vibration of beam the generalized deflection becomes

$$W(x) = c_1 w_1(x) + c_2 w_2(x) + \cdots + c_n w_n(x)$$

where  $w_1(x)$ ,  $w_2(x)$ , ...  $w_n(x)$  are the admissible function of the spatial variable x, which satisfy the boundary condition of the structure.

• The constants  $c_i$  are the arbitrary constants to be determined to have best possible mode shapes in combination of  $w_i(x)$ .

- To obtain the constants c<sub>i</sub>, natural frequency is made stationary at natural modes.
- The partial derivative of Rayleig quotient w.r.t. constants  $c_i$  are made to zero.

$$\frac{\partial(\omega^2)}{\partial c_i} = 0, \qquad i = 1, 2, 3, \dots, n$$

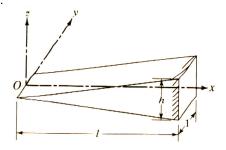
- The above equation denotes a set of n linear algebraic equation in the coefficients c<sub>1</sub>, c<sub>2</sub>,..., c<sub>n</sub> and also contains the undetermined quantity ω<sup>2</sup>.
- It is an eigenvalue problem to yield n natural frequencies and n natural modes.
- The i-th mode with respect to the i-th natural frequency

$$\{C^{(i)}\} = \left\{c_1^{(i)} \ c_2^{(i)} \ c_3^{(i)} \ \dots \ c_n^{(i)}\right\}^T$$

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# Find the natural frequencies of transverse vibration of the nonuniform cantilever beam shown below using the deflection shapes

$$w_1(x) = \left(1 - \frac{x}{l}\right)^2$$
 and  $w_2(x) = \frac{x}{l} \left(1 - \frac{x}{l}\right)^2$ 



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The cross sectional are and the moment of inertia of the transverse cross section about centroidal axis are

$$A(x) = \frac{hx}{l} \quad and \quad I(x) = \frac{1}{12} \left(\frac{hx}{l}\right)^3$$
$$W(x) = c_1 \left(1 - \frac{x}{l}\right)^2 + c_2 \frac{x}{l} \left(1 - \frac{x}{l}\right)^2$$

Rayleigh's quotient

$$R(W(x)) = \omega^2 = \frac{\int_0^l EI(x) \left(\frac{d^2 W(x)}{dx^2}\right)^2 dx}{\int_0^l \rho A(x) W^2(x) dx} = \frac{X}{Y}$$

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The condition that make  $\omega^2$  or R(W(x)) stationary are

$$\frac{\partial(\omega^2)}{\partial c_1} = \frac{Y\frac{\partial X}{\partial c_1} - X\frac{\partial Y}{\partial c_1}}{Y^2} = 0$$

$$\frac{\partial(\omega^2)}{\partial c_2} = \frac{Y\frac{\partial X}{\partial c_2} - X\frac{\partial Y}{\partial c_2}}{Y^2} = 0$$

May be rewritten as

$$\frac{\partial X}{\partial c_1} - \frac{X}{Y} \frac{\partial Y}{\partial c_1} = \frac{\partial X}{\partial c_1} - \omega^2 \frac{\partial Y}{\partial c_1} = 0$$
$$\frac{\partial X}{\partial c_2} - \frac{X}{Y} \frac{\partial Y}{\partial c_2} = \frac{\partial X}{\partial c_2} - \omega^2 \frac{\partial Y}{\partial c_2} = 0$$

Evaluating the X and Y,

$$X = \frac{Eh^3}{3l^3} \left( \frac{c_1^2}{4} + \frac{c_2^2}{10} + \frac{c_1c_2}{5} \right) \text{ and } Y = \rho hl \left( \frac{c_1^2}{30} + \frac{c_2^2}{280} + \frac{2c_1c_2}{105} \right)$$

The algebraic equations become

$$\begin{bmatrix} \left(\frac{1}{2} - \bar{\omega}^2 \frac{1}{15}\right) & \left(\frac{1}{5} - \bar{\omega}^2 \frac{2}{105}\right) \\ \left(\frac{1}{5} - \bar{\omega}^2 \frac{2}{105}\right) & \left(\frac{1}{5} - \bar{\omega}^2 \frac{2}{140}\right) \end{bmatrix} \begin{cases} c_1 \\ c_2 \end{cases} = \begin{cases} 0 \\ 0 \end{cases}$$

where,  $\ \ \, \bar{\omega}^2 = \frac{3\omega^2 
ho l^4}{E \hbar^2}$  By setting determinant equal to zero

$$\frac{1}{8820}\bar{\omega}^4 - \frac{13}{1400}\bar{\omega}^2 + \frac{3}{50} = 0$$

$$\bar{\omega}_1 = 2.6599 \quad \Rightarrow \quad \omega_1 \simeq 1.5367 \left(\frac{Eh^2}{\rho l^4}\right)^{1/2}$$

$$ar{\omega}_1 = 8.6492 \quad \Rightarrow \quad \omega_1 \simeq 4.9936 \left(rac{Eh^2}{
ho l^4}
ight)^{1/2}$$

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